

On the positive definite solutions of the nonlinear  
matrix equations  $X^p = A \pm M^T (X^{-1} \# B)^{-1} M$

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- Introduction and preliminary
- Solvability of the nonlinear matrix equations
  - Existence and uniqueness
  - Lower and upper bound
  - Iteration method
- Numerical examples

Recently, varieties of nonlinear matrix equations have been studied, for example

- $X - A^* e^X A = I$ , [1]
- $X \pm \sum_{i=1}^m A_i^* X^{-q} A_i = Q$ , [2,3,4]
- $A_0 + \sum_{i=1}^k \sigma_i A_i^* X^{p_i} A_i = 0$ , ( $\sigma_i = \pm 1$ ), [5,6]

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<sup>1</sup>D.J. Gao, On Hermitian positive definite solutions of the nonlinear matrix equation  $X - A^* e^X A = I$ , J. Appl. Math. Comput. 50 (2016) 109–116.

<sup>2</sup>X. Yin, R. Wen, L. Fang, On the nonlinear matrix equation  $X + \sum_{i=1}^m A_i^* X^{-q} A_i = Q$  ( $0 < q \leq 1$ ), Bull. Korean Math. Soc. 51 (2014) 739–763.

<sup>3</sup>X.Y. Yin, S.Y. Liu, Positive definite solutions of the matrix equations  $X \pm A^* X^{-q} A = Q$  ( $q \geq 1$ ), Comput. Math. Appl. 59 (2010) 3727–3739.

<sup>4</sup>L. Zhang, An improved inversion-free method for solving the matrix equation  $X + A^* X^{-\alpha} A = Q$ , J. Comput. Appl. Math. 253 (2013) 200–203.

<sup>5</sup>M. Konstantinov, P. Petkov, I. Popchev, V. Angelova, Sensitivity of the matrix equation  $A_0 + \sum_{i=1}^k \sigma_i A_i X^{p_i} A_i = 0$  ( $\sigma_i = \pm 1$ ), Appl. Comput. Math. 10 (2011) 409–427.

<sup>6</sup>I. Popchev, M. Konstantinov, P. Petkov, V. Angelova, Norm-wise, mixed and component-wise condition numbers of matrix equation  $A_0 + \sum_{i=1}^k \sigma_i A_i X^{p_i} A_i = 0$  ( $\sigma_i = \pm 1$ ), Appl. Comput. Math. 14 (2014) 18–30.

- $X - \sum_{i=1}^m A_i^* X^{-1} A_i = Q$ , [7,8]
- $X - A^*(X^{-1} + M)^{-1} A = Q$ , [9]
- $X^s + \sum_{i=1}^m A_i^* X^{-t_i} A_i = Q$ , [10]
- ...

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<sup>7</sup>J. Li, Y. Zhang, Sensitivity analysis of the matrix equation from interpolation problem, J. Appl. Math. 2013 (2013) ID 518269, 8 pages.

<sup>8</sup>X.Y. Yin, F. Liang, Perturbation analysis for the positive definite solution of the nonlinear matrix equation  $X - \sum_{i=1}^m A_i X^{-1} A_i = Q$ , J. Appl. Math. Comput. 43 (2013) 199–211.

<sup>9</sup>B.C. Levy, M. Zorzi, A contraction analysis of the convergence of risk-sensitive filters. SIAM J. Optimization Control. 54 (2016) 2154–2173.

<sup>10</sup>A.J. Liu, G.L. Chen, On the Hermitian positive definite solutions of nonlinear matrix equation  $X^s + \sum_{i=1}^m A_i X^{-t_i} A_i = Q$ , Appl. Math. Comput. 243 (2014) 950–959.

We consider the nonlinear matrix equations

$$X^p = A + M^T(X^{-1}\#B)^{-1}M, \quad (1)$$

and

$$X^p = A - M^T(X^{-1}\#B)^{-1}M, \quad (2)$$

where  $p \geq 1$  is a positive integer,  $A, B, M \in \mathbb{R}^{n \times n}$ ,  $M$  is a nonsingular matrix,  $A$  is positive semidefinite and  $B$  is positive definite.

# Introduction

We call  $C\#D$  the geometric mean of positive definite matrices  $C$  and  $D$ , which is extended by T. Ando [11] from the case of two positive scalars to the case of positive semidefinite operators.

- The geometric mean of positive real numbers  $a$  and  $b$  is  $\sqrt{ab}$ .
- The geometric mean of positive definite matrices  $C$  and  $D$  is defined as<sup>[12,13]</sup>

$$C\#D := C^{1/2}(C^{-1/2}DC^{-1/2})^{1/2}C^{1/2}.$$

- This definition could be extended to positive semidefinite matrices  $C$  and  $D$  by a limit from above<sup>[14]</sup>

$$C\#D := \lim_{\varepsilon \rightarrow 0} (C + \varepsilon I)\#(D + \varepsilon I).$$

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<sup>11</sup>T. Ando, Concavity of certain maps on positive definite matrices and applications to Hadamard products, *Linear Algebra Appl.* 26 (1979) 203–241.

<sup>12</sup>R. Bhatia, On the exponential metric increasing property, *Linear Algebra Appl.* 375 (2003) 211–220.

<sup>13</sup>J.D. Lawson, Y. Lim, The geometric mean, matrices, metrics, and more, *Am. Math. Monthly* 108 (2001) 797–812.

<sup>14</sup>R. Bhatia, *Positive Definite Matrices*, Princeton University Press, Princeton, 2007.

For positive definite matrices  $A$  and  $B$ , the Riccati equation  $XA^{-1}X = B$  has a unique positive definite solution  $X$ , which can be expressed as  $X = A\#B$ .

For  $p = 1$ , we find that  $X$  is a positive definite solution of equation (1) (equation (2)) if and only if  $Y = B^{\frac{1}{2}}XB^{\frac{1}{2}}$  is a positive definite solution of the nonlinear matrix equation

$$Y = A_1 + M_1^T Y^{\frac{1}{2}} M_1 \quad (Y = A_1 - M_1^T Y^{\frac{1}{2}} M_1),$$

where  $A_1 = B^{-\frac{1}{2}}AB^{-\frac{1}{2}}$  and  $M_1 = B^{\frac{1}{2}}MB^{-\frac{1}{2}}$ . This matrix equation has been studied in [15,16,17].

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<sup>15</sup> M. Konstantinov, P. Petkov, I. Popchev, V. Angelova, Sensitivity of the matrix equation  $A_0 + \sum_{i=1}^k \sigma_i A_i X^{p_i} A_i = 0$  ( $\sigma_i = \pm 1$ ), Appl. Comput. Math. 10 (2011) 409–427.

<sup>16</sup> I. Popchev, M. Konstantinov, P. Petkov, V. Angelova, Norm-wise, mixed and component-wise condition numbers of matrix equation  $A_0 + \sum_{i=1}^k \sigma_i A_i X^{p_i} A_i = 0$  ( $\sigma_i = \pm 1$ ), Appl. Comput. Math. 14 (2014) 18–30.

<sup>17</sup> A.J. Liu, G.L. Chen, On the Hermitian positive definite solutions of nonlinear matrix equation  $X^s + \sum_{i=1}^m A_i X^{-t_i} A_i = Q$ , Appl. Math. Comput. 243 (2014) 950–959.



We also found that if  $A$  is a positive definite matrix and the nonlinear matrix equation

$$X = A(X^{-1} \# A^2)^{-1} A \quad (3)$$

has a positive definite solution  $X$ , then  $X$  also solves equation  $AXA = XAX$ , a special case of the Yang-Baxter equation which plays an important role in topics of statistical mechanics, braid groups and knot theory, see [18,19,20,21] and the references therein.

Note that equation (3) is a special case of equation (1).

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<sup>18</sup>C.N. Yang, Some exact results for the many-body problem in one dimension with repulsive delta-function interaction, Phys. Rev. Lett. 19 (1967) 1312-1315.

<sup>19</sup>R.J. Baxter, Partition function of the eight-vertex lattice model, Ann. Phys. 70 (1972) 193-228.

<sup>20</sup>F. Felix, Nonlinear Equations, Quantum Groups and Duality Theorems: A Primer on the Yang-Baxter Equation, VDM Verlag, 2009.

<sup>21</sup>C. Yang, M. Ge, Braid Group, Knot Theory, and Statistical Mechanics, World Scientific, 1989.

It is well-known that for positive definite matrices  $A$  and  $B$ ,

$$(A\#B)^{-1} = A^{-1}\#B^{-1}.$$

Hence, the nonlinear matrix equations (1) and (2) can be written as

$$X^P = A + M^T(X\#B^{-1})M, \quad (4)$$

and

$$X^P = A - M^T(X\#B^{-1})M, \quad (5)$$

Note that  $B^{-1}$  in equations (4) and (5) is still positive definite, without loss of generality, we study the nonlinear matrix equations

$$X^p = A + M^T(X \# B)M, \quad (6)$$

and

$$X^p = A - M^T(X \# B)M, \quad (7)$$

where  $p \geq 1$  is a positive integer,  $M$  is an  $n \times n$  nonsingular matrix,  $A$  is a positive semidefinite matrix and  $B$  is a positive definite matrix.

- $\mathbb{R}^{n \times n}$ : the set of  $n \times n$  matrices with elements on field  $\mathbb{R}$ .
- $P(n)$ : the set of  $n \times n$  symmetric positive definite matrices.
- $\|\cdot\|$ : the spectral norm.
- For a matrix  $H$ ,  $\lambda_{\max}(H)$  ( $\lambda_{\min}(H)$ ) denotes the maximal (minimal) eigenvalue of  $H$ .
- For Hermitian matrices  $X$  and  $Y$ ,  $X \geq Y$  ( $X > Y$ ) means that  $X - Y$  is positive semidefinite (definite).

The Thompson metric on  $P(n)$  is defined by

$$d(A, B) = \max\{\log M(A/B), \log M(B/A)\},$$

where  $M(A/B) = \inf\{\lambda > 0 : A \leq \lambda B\} = \lambda_{\max}(B^{-\frac{1}{2}}AB^{-\frac{1}{2}})$ .

It can be obtained from [19] that  $P(n)$  is a complete metric space with respect to the Thompson metric.

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<sup>22</sup>R.D. Nussbaum, Hilbert's projective metric and iterated nonlinear maps, *Memoirs of Amer. Math. Soc.* 75 (1988), no. 391.

# Preliminaries

## Lemma [Thompson, 1963]

For any  $X, Y \in P(n)$  and any  $n \times n$  nonsingular matrix  $M$ , it holds

$$d(X, Y) = d(X^{-1}, Y^{-1}) = d(M^T X M, M^T Y M),$$

and

$$d(X^r, Y^r) \leq |r|d(X, Y), \quad r \in [-1, 1].$$

## Lemma [Lim, 2011]

For any  $A, B, C, D \in P(n)$ ,

$$d(A + B, C + D) \leq \max\{d(A, C), d(B, D)\}.$$

Especially,

$$d(A + B, A + C) \leq d(B, C).$$

lemma [Harmonic-geometric-arithmetic mean inequality]

For two positive definite matrices  $A$  and  $B$ , the harmonic-geometric-arithmetic mean inequality holds

$$2(A^{-1} + B^{-1})^{-1} \leq A\#B \leq (A + B)/2.$$

# Solvability of the nonlinear matrix equation

$$X^p = A + M^T(X \# B)M$$

## Theorem

Matrix equation (6) always has a unique positive definite solution  $X_+$ . The matrix sequence  $\{X_k\}$  generated by the iteration

$$\forall X_0 \in P(n), \quad X_{k+1} = (A + M^T(X_k \# B)M)^{\frac{1}{p}} \quad (8)$$

converges to  $X_+$ .

**Proof:** Define a map  $g : P(n) \rightarrow P(n)$  by

$$g(X) = (A + M^T(X \# B)M)^{\frac{1}{p}}.$$



For any  $X, Y \in P(n)$ , under Thompson metric, we have

$$\begin{aligned}d(g(X), g(Y)) &= d((A + M^T(X\#B)M)^{\frac{1}{p}}, (A + M^T(Y\#B)M)^{\frac{1}{p}}) \\ &\leq \frac{1}{p}d(M^T(X\#B)M, M^T(Y\#B)M) \\ &\leq \frac{1}{p}d(X\#B, Y\#B) \\ &\leq \frac{1}{2p}d(X, Y),\end{aligned}$$

which shows that the map  $g$  is a strict contraction for Thompson metric with the contraction constant  $\frac{1}{2p}$ . Based on the Banach fixed point theorem, there is a unique  $X_+ \in P(n)$  such that  $X_+ = g(X_+)$ , that is,  $X_+$  is the unique positive definite solution of equation (6), and for every  $X_0 \in P(n)$ , the iterative sequence  $\{X_k\}$  generated by (8) converges to  $X_+$ .  $\square$

# Numerical example

Let

$$A = \begin{pmatrix} 0.0120 & -0.0030 & 0.0010 \\ -0.0030 & 0.0210 & 0.0020 \\ 0.0010 & 0.0020 & 0.0070 \end{pmatrix}, B = \begin{pmatrix} 1.1231 & 0.4497 & 0.9024 \\ 0.4497 & 0.8283 & 0.7254 \\ 0.9024 & 0.7254 & 1.0292 \end{pmatrix},$$

$$M = \begin{pmatrix} 0.7922 & 0.0357 & 0.6787 \\ 0.9594 & 0.8491 & 0.7577 \\ 0.6557 & 0.9339 & 0.7431 \end{pmatrix}, \text{ and } p = 2, 3, 4, 5, 6, 7. \text{ We apply}$$

the fixed-point iteration (8) with starting point  $X_0 = I$  to equation (6). The results are shown in Figure 1.

# Numerical example

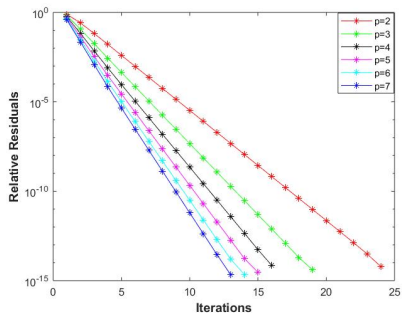


Figure 1: Convergence behaviour of the fixed-point iteration (8).

## A lower and an upper bound

We obtain a lower and an upper bound of the unique positive definite solution of equation (6). To this end, we consider the following two auxiliary nonlinear matrix equations:

$$X^p = A + M^T(X^{-1} + B^{-1})^{-1}M \quad (9)$$

and

$$X^p = A + M^T B M + M^T X M, \quad (10)$$

where  $p, A, M$  and  $B$  are defined the same as in equation (6).

For  $p \geq 2$  is a positive integer, it can be deduced directly from Corollary 3.6 in [23] that equations (9) and (10) have a unique positive definite solution  $X_*$  and  $X_{**}$ , respectively.

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<sup>23</sup> C. Jung, H.-M. Kim, Y. Lim, On the solution of the nonlinear matrix equation  $X^n = f(X)$ , Linear Algebra Appl. 430 (2009) 2042-2052.

# A lower and an upper bound

## Theorem

Suppose  $p \geq 2$  is a positive integer, then the unique positive definite solution  $X_+$  of equation (6) satisfies

$$X_* \leq X_+ \leq X_{**}. \quad (11)$$

# A lower and an upper bound

## Theorem

*For  $p = 1$ , let  $X_*$  and  $X_{**}$  be the unique positive definite solution of equation (9) and equation (10), respectively, we have the following results:*

- (i) if both  $A$  and  $B$  are positive definite matrices, then  $X_* \leq X_+$ ;*
- (ii) if  $\rho(M^T M) < 1$ , then  $X_+ \leq X_{**}$ .*

# A lower and an upper bound

Although inequality (11) gives a lower and an upper bound of the unique positive definite solution  $X_+$  of equation (6), **the computation of  $X_*$  and  $X_{**}$  is nontrivial**. Hence, finding a more explicit lower and upper bound which can be easily to compute is interesting.

## Theorem

Suppose  $p \geq 2$  is a positive integer, then the unique positive definite solution  $X_+$  of equation (6) satisfies

$$\alpha_1 I \leq X_+ \leq \alpha_2 I, \quad (12)$$

where  $\alpha_1$  and  $\alpha_2$  are, respectively, the unique positive roots of functions

$$f_1(x) = x^p - \lambda_{\min}(M^T M)(x^{-1} + \lambda_{\min}^{-1}(B))^{-1} - \lambda_{\min}(A)$$

and

$$h_2(x) = x^p - \lambda_{\max}(M^T M)x - \lambda_{\max}(A + M^T B M).$$



# Numerical example

Let  $B = I_n$ ,  $M = rand(n)$  and  $A = \begin{pmatrix} 3 & -1 & & & \\ -1 & 3 & -1 & & \\ & \ddots & \ddots & \ddots & \\ & & -1 & 3 & -1 \\ & & & -1 & 3 \end{pmatrix}_{n \times n}$ .

Set  $p = 3$  and  $n = 3, 4, \dots, 8$ , we compute the lower and upper bound (12) of the unique positive definite solution of equation (6). The results are displayed in Table 1.

# Numerical example

$n$	lower bound $\alpha_1/$	$\lambda_{\min}(X_+)//$	$\lambda_{\max}(X_+)//$	upper bound $\alpha_2/$
3	1.3010/	1.7223/	2.0196/	2.5338/
4	1.2088/	1.5668/	2.1393/	2.6423/
5	1.1548/	1.4617/	2.2467/	3.0514/
6	1.1207/	1.4200/	2.5952/	3.6310/
7	1.0928/	1.3258/	2.8757/	4.1136/
8	1.0747/	1.3536/	3.1530/	4.5773/

Table 1: Estimate (12) of the unique positive definite solution of equation (6).

# Perturbation analysis

For the case when both  $A$  and  $B$  are perturbed by  $\Delta A$  and  $\Delta B$ , respectively, we have the following theorem.

## Theorem

*Suppose the matrices  $A$  and  $B$  are perturbed by  $\Delta A$  and  $\Delta B$ , respectively, where  $A + \Delta A$  is symmetric positive semidefinite and  $B + \Delta B$  is symmetric positive definite. Let  $X$  and  $\tilde{X}$  be, respectively, the unique positive definite solution of equation (6) and the corresponding perturbed matrix equation. Then,*

$$\frac{\|\tilde{X} - X\|}{\|X\|} \leq e^\sigma - 1, \quad (13)$$

where  $\sigma = \frac{1}{p}d(\hat{A}, A) + \frac{1}{2p-1}d(\hat{B}, B)$ .

# Example

$$A = \begin{pmatrix} 0.0120 & -0.0030 & 0.0010 \\ -0.0030 & 0.0210 & 0.0020 \\ 0.0010 & 0.0020 & 0.0070 \end{pmatrix}, B = \begin{pmatrix} 1.1231 & 0.4497 & 0.9024 \\ 0.4497 & 0.8283 & 0.7254 \\ 0.9024 & 0.7254 & 1.0292 \end{pmatrix},$$

$$M = \begin{pmatrix} 0.7922 & 0.0357 & 0.6787 \\ 0.9594 & 0.8491 & 0.7577 \\ 0.6557 & 0.9339 & 0.7431 \end{pmatrix}.$$

Let

$$\Delta A = \begin{pmatrix} 0.5 & 0.1 & 0.2 \\ 0.1 & 0.7 & 0.3 \\ 0.2 & 0.3 & 1 \end{pmatrix} \times 10^{-j}, \quad \Delta B = \begin{pmatrix} 2 & 0.5 & 0.2 \\ 0.5 & 1 & 0.5 \\ 0.2 & 0.5 & 2 \end{pmatrix} \times 10^{-j}.$$

# Example

$p$	$j = 3$		$j = 7$		$j = 10$	
	$\frac{\ \Delta X\ }{\ X\ }$	$e^\sigma - 1$	$\frac{\ \Delta X\ }{\ X\ }$	$e^\sigma - 1$	$\frac{\ \Delta X\ }{\ X\ }$	$e^\sigma - 1$
2	9.38e-04	7.84e-02	9.59e-08	8.03e-06	9.59e-11	8.03e-09
3	1.35e-03	5.10e-02	1.37e-07	5.29e-06	1.37e-10	5.29e-09
4	1.36e-03	378e-02	1.38e-07	3.95e-06	1.38e-10	3.95e-09
5	1.27e-03	3.01e-02	1.30e-07	3.15e-06	1.30e-10	3.15e-09
6	1.17e-03	2.49e-02	1.19e-07	2.62e-06	1.19e-10	2.62e-09

Table 2: Perturbation bounds (13) for the different  $p$  and  $j$ .

# Solvability of the nonlinear matrix equation

$$X^p = A - M^T(X \# B)M$$

## Theorem

If  $M^T(A^{\frac{1}{p}} \# B)M < A$ , then equation (7) has a positive definite solution.

Let  $\eta = \lambda_{\max}(A)$ ,  $\zeta = \lambda_{\min}(A) - \eta^{\frac{1}{2p}} \lambda_{\max}(M^T M) \lambda_{\max}^{\frac{1}{2}}(B)$ , if  $p\zeta^{1-\frac{1}{2p}} > \frac{\|M\|^2 \|B\|^{3/2} \|B^{-1}\|}{2}$ , then the positive definite solution of (7) is unique and it satisfies that

$$\alpha \zeta^{\frac{1}{p}} I \leq X_+ \leq \beta \eta^{\frac{1}{p}} I,$$

where  $X_+$  is the unique positive definite solution of equation (7),  $\alpha$  and  $\beta$  are positive solutions of the following equations

$$\begin{cases} \alpha = \frac{\lambda_{\min}^{\frac{1}{p}}(A - \beta^{\frac{1}{2}} \eta^{\frac{1}{2p}} M^T B^{\frac{1}{2}} M)}{\lambda_{\min}^{\frac{1}{2p}}(A - \zeta^{\frac{1}{2p}} M^T B^{\frac{1}{2}} M)}, \\ \beta = \frac{\lambda_{\max}^{\frac{1}{p}}(A - \alpha \zeta^{\frac{1}{2p}} M^T B^{\frac{1}{2}} M)}{\eta^{\frac{1}{p}}}. \end{cases}$$

Consider the iteration

$$\begin{cases} X_0 = \beta \eta^{\frac{1}{p}} I, \\ X_{k+1} = (A - M^T (X_k \# B) M)^{\frac{1}{p}}. \end{cases} \quad (14)$$

### Theorem

*If  $\zeta = \lambda_{\min}(A) - \lambda_{\max}(M^T M) \lambda_{\max}^{\frac{1}{2p}}(A) \lambda_{\min}^{\frac{1}{2}}(B) > 0$  and  $p \zeta^{1 - \frac{1}{2p}} \geq \frac{\|M\|^2 \|B\|^{\frac{3}{2}} \|B^{-1}\|}{2}$ , then the subsequences  $\{X_{2k}\}$  and  $\{X_{2k+1}\}$  generated by iteration (14) both converge to the unique positive definite solution  $X_+$  of equation (7), and it satisfies that*

$$X_{2k+1} \leq X_+ \leq X_{2k}, \quad k = 0, 1, \dots$$

**Thank you for your attention!**