

# fractional-Tikhonov and graph-Laplacian approximation applied to signal and image restoration



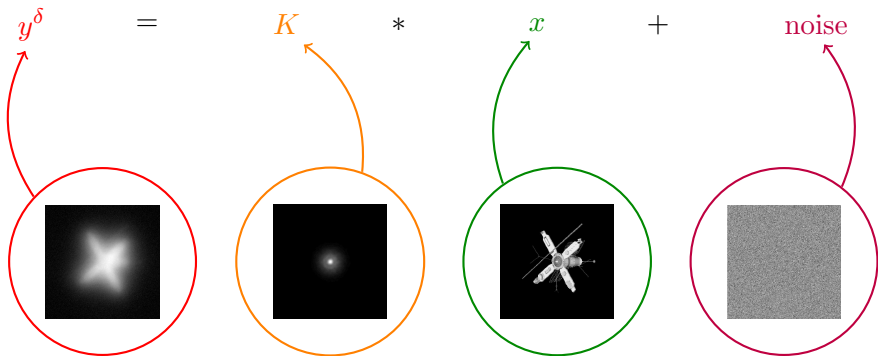
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Dip. di Scienze e Alta Tecnologia

Kalamata, 2<sup>nd</sup> of July 2018

## Our model problem

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- $K$  represents the blur and it is severely ill-conditioned (compact integral operator of the first kind);
- $y^\delta$  are known measured data (blurred and noisy image);
- $\|\text{noise}\| \leq \delta$ .

## Filter based regularization methods

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We substitute the  $K^\dagger$  operator with a one-parameter family of continuous linear operators  $\{R_\alpha\}_{\alpha \in (0, \alpha_0)}$ ,

$$K^\dagger y^\delta = \sum_{m: \sigma_m > 0} \sigma_m^{-1} \langle y^\delta, u_m \rangle v_m$$

$\Downarrow$

$$R_\alpha y^\delta = \sum_{m: \sigma_m > 0} F_\alpha(\sigma_m) \sigma_m^{-1} \langle y^\delta, u_m \rangle v_m$$

$\alpha = \alpha(\delta, y^\delta)$  is called rule choice.

## Fractional Tikhonov filter functions

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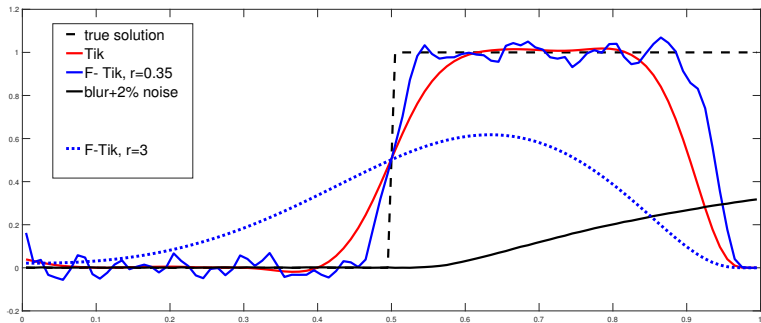
- **Standard** Tikhonov filter:  $F_{\alpha}(\sigma_m) = \frac{\sigma_m^2}{\sigma_m^2 + \alpha}$ , with  $\alpha > 0$ .
- **Weighted/Fractional** Tikhonov filter:  $F_{\alpha,r}(\sigma_m) = \frac{\sigma_m^{r+1}}{\sigma_m^{r+1} + \alpha}$ , with  $\alpha > 0$  and  $r \in [0, +\infty)$  (Hochstenbach and Reichel, 2011).

For  $0 \leq r < 1$ , fractional weighted filter **smooths** the reconstructed solution **less** than standard Tikhonov while for  $r > 1$  it **oversmooths**.

## An easy 1d example of oversmoothing - part 1

Blur taken from  $Heat(n, \kappa)$  in Regtools,  $n = 100, \kappa = 1$  and 2% noise. True solution:

$$\mathbf{x}^\dagger : [0, 1] \rightarrow \mathbb{R} \quad \text{s.t.} \quad \mathbf{x}^\dagger(t) = \begin{cases} 0 & \text{if } 0 \leq t \leq 0.5, \\ 1 & \text{if } 0.5 < t \leq 1. \end{cases}$$



## Let's reformulate the problem

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- Tikhonov:  $\operatorname{argmin}_{\mathbf{x} \in \mathbb{R}^n} \|K\mathbf{x} - \mathbf{y}\|_2^2 + \alpha\|\mathbf{x}\|_2^2$

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- F. Tikhonov:  $\operatorname{argmin}_{\mathbf{x} \in \mathbb{R}^n} \|K\mathbf{x} - \mathbf{y}\|_W^2 + \alpha \|\mathbf{x}\|_2^2$ , with  $W = (KK^*)^{\frac{r-1}{2}}$ .

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- Generalized Tikhonov:  $\operatorname{argmin}_{\mathbf{x} \in \mathbb{R}^n} \|K\mathbf{x} - \mathbf{y}\|_2^2 + \alpha \|L\mathbf{x}\|_2^2$ , with  $L$  semi-positive definite and  $\ker(L) \cap \ker(K) = \vec{0}$ .  $\ker(L)$  should 'approximate the features' of  $\mathbf{x}^\dagger$ .



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- Generalized F. Tikhonov:  $\operatorname{argmin}_{\mathbf{x} \in \mathbb{R}^n} \|K\mathbf{x} - \mathbf{y}\|_W^2 + \alpha \|L\mathbf{x}\|_2^2$

## Laplacian - Finite Difference approximation

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Poisson (Sturm-Liouville) problem on  $[0, 1]$ :

$$\begin{cases} -\Delta \mathbf{x}(t) = \mathbf{f}(t) & t \in (0, 1), \\ \alpha_1 \mathbf{x}(0) + \beta_1 \mathbf{x}'(0) = \gamma_1, \\ \alpha_2 \mathbf{x}(1) + \beta_2 \mathbf{x}'(1) = \gamma_2. \end{cases}$$

If we consider **Dirichlet** homogeneous boundary conditions ( $\mathbf{x}(0) = \mathbf{x}(1) = 0$ ) and **3-point** stencil FD approximation:

$$-\Delta \mathbf{x}(t) \approx \frac{-\mathbf{x}(t-h) + 2\mathbf{x}(t) - \mathbf{x}(t+h)}{h^2}, \quad h^2 = n^{-2},$$

$$-L = \begin{bmatrix} 2 & -1 & 0 & \cdots \\ -1 & 2 & -1 & \cdots \\ & \ddots & \ddots & \ddots \\ & & 0 & -1 & 2 \end{bmatrix} \quad \ker(L) = \vec{0}.$$

## Laplacian - Finite Difference approximation

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If we consider **Neumann** homogeneous boundary conditions ( $\mathbf{x}'(0) = \mathbf{x}'(1) = 0$ ) and **3-point** stencil FD approximation:

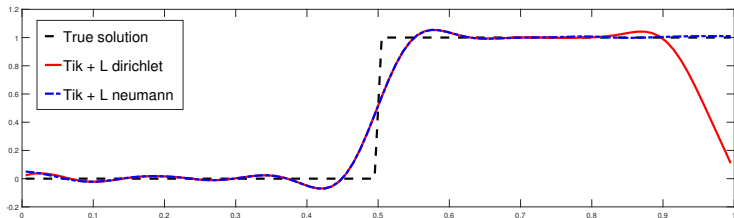
$$-\Delta \mathbf{x}(t) \approx \frac{-\mathbf{x}(t-h) + 2\mathbf{x}(t) - \mathbf{x}(t+h)}{h^2}, \quad h^2 = n^{-2},$$

$$-L = \begin{bmatrix} \mathbf{1} & -1 & 0 & \cdots \\ -1 & 2 & -1 & \cdots \\ & \ddots & \ddots & \ddots \\ & 0 & -1 & \mathbf{1} \end{bmatrix} \quad \ker(L) = \text{Span}\{\vec{\mathbf{1}}\}.$$

## An easy 1d example of oversmoothing - part 2

Blur taken from  $Heat(n, \kappa)$  in Regtools,  $n = 100, \kappa = 1$  and 2% noise. True solution:

$$\mathbf{x}^\dagger : [0, 1] \rightarrow \mathbb{R} \quad \text{s.t.} \quad \mathbf{x}^\dagger(t) = \begin{cases} 0 & \text{if } 0 \leq t \leq 0.5, \\ 1 & \text{if } 0.5 < t \leq 1. \end{cases}$$



# Graph Laplacian

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- An image/signal  $\mathbf{x}$  can be represented by a weighted undirected graph  $\mathcal{G} = (V, E, w)$ :
  - the **nodes**  $v_i \in V$  are the pixels of the image/signal and  $\mathbf{x}_i \geq 0$  is the color intensity of  $\mathbf{x}$  at  $v_i$ .
  - an **edge**  $e_{i,j} \in E \subseteq V \times V$  exists if the pixels  $v_i$  and  $v_j$  are connected, i.e.,  $v_i \sim v_j$ .
  - $w : E \rightarrow \mathbb{R}$  is a similarity (positive) **weight** function,  $w(e_{i,j}) = w_{i,j}$ .
- The **graph Laplacian** is defined as

$$-\Delta_w^{(n)} \mathbf{x}_i = \sum_{v_j \sim v_i} w_{i,j} (\mathbf{x}_i - \mathbf{x}_j), \quad \begin{cases} w_{i,j} > 0 & \text{if } v_j \sim v_i, \\ w_{i,j} = 0 & \text{otherwise.} \end{cases}$$

## Graph Laplacian - Example

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**Example.** In the  $1d$  case, if we define

$$v_i \sim v_j \text{ iff } i = j + 1 \text{ or } i = j - 1, \quad w_{i,j} = \begin{cases} 1 & \text{if } v_i \sim v_j, \\ 0 & \text{otherwise,} \end{cases}$$

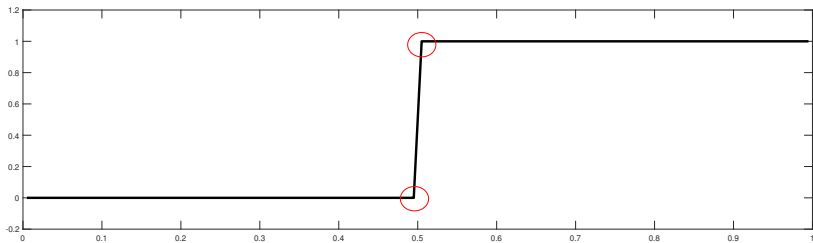
then it holds

$$-\Delta_w^{(n)} = L_w^{(n)} = \begin{bmatrix} 1 & -1 & 0 & \cdots \\ -1 & 2 & -1 & \cdots \\ & \ddots & \ddots & \ddots \\ & 0 & -1 & 1 \end{bmatrix}.$$

# Question

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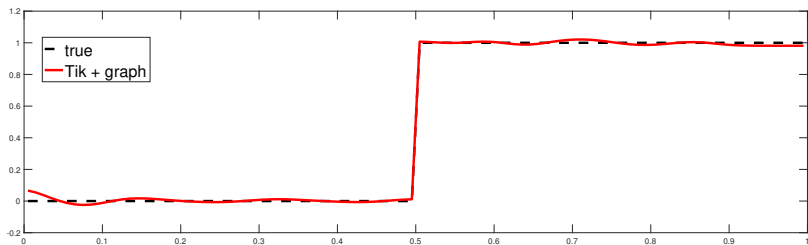
**Why should the red points be connected?**



# Answer

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They should not, indeed

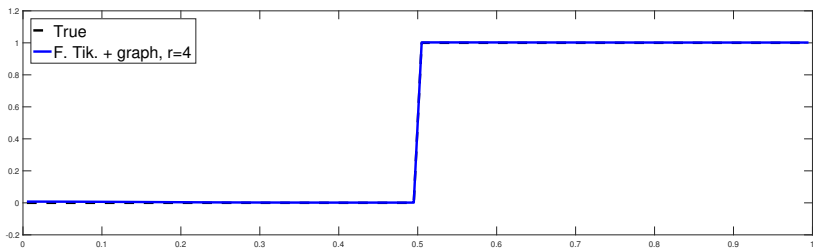


$$L_w^{(n)} = \begin{bmatrix} L_w^{(n/2)} & 0 \\ 0 & L_w^{(n/2)} \end{bmatrix}$$



# Fractional Tikhonov + Graph Laplacian

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# Problems

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- Detection of the discontinuity points.

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- Choice of the weights  $w_{i,j}$ .

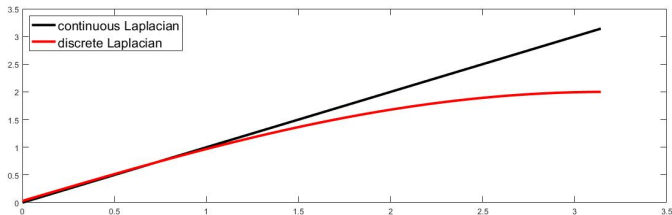
# Problems

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- Detection of the discontinuity points.
  - pre-denoising + first derivatives?
- SVD decomposition for the fractional-Tikhonov.
  - we need to bypass it finding a new smoothing parameter.
- Choice of the weights  $w_{i,j}$ .
  - finding the best weights that can approximate the Euclidean Laplacian.

## Approximating the continuous Laplacian by graphs

$$-L_w^{(n)} = \begin{bmatrix} 1 & -1 & 0 & \cdots \\ -1 & 2 & -1 & \cdots \\ & \ddots & \ddots & \ddots \\ & & 0 & -1 & 1 \end{bmatrix} \Rightarrow \lambda_j(L_w^{(n)}) = 2 - 2 \cos\left(\frac{(j-1)\pi}{n}\right)$$



## FD approximation - 1/3

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We have already highlighted that

Finite Difference 3-point stencil  $\iff$  graph-Laplacian

Can we argue the same relationship if we use a wider stencil, i.e., if we "connect" more points?

## FD approximation - 2/3

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Let us use a 5-point stencil.

$$-\Delta \mathbf{x}(t) \approx \frac{\mathbf{x}(t-2h) - 16\mathbf{x}(t-h) + 30\mathbf{x}(t) - 16\mathbf{x}(t+h) + \mathbf{x}(t+2h)}{12h^2},$$

then

$$-L_w^{(n)} = -L_w^{(n)} = \begin{bmatrix} \frac{15}{12} & -\frac{16}{12} & \frac{1}{12} & 0 & \dots & & \\ -\frac{16}{12} & \frac{31}{12} & -\frac{16}{12} & \frac{1}{12} & 0 & \dots & \\ \dots & \frac{1}{12} & -\frac{16}{12} & \frac{30}{12} & -\frac{16}{12} & \frac{1}{12} & \dots \\ & & & \ddots & \ddots & & \end{bmatrix}.$$



## FD approximation 3/3

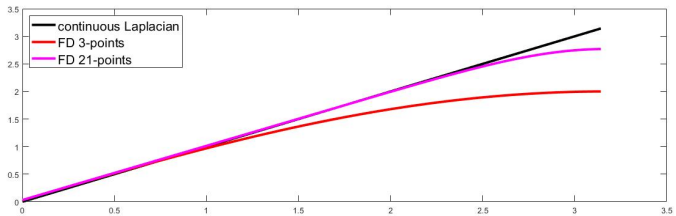
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We have seen that **negative** weights appear. Does it make sense?

- Does it approximate better the continuous Laplacian? **Yes.**
- Is it still a graph-Laplacian? **Yes.**
- Does it improve the reconstruction of our signal/image? **Yes.**

# Spectral approximation

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## graph-Laplacian - distributional point of view

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$$\begin{aligned} -\mathbf{x}''(t_0) &= \langle \mathbf{x}''(t), \delta_{t_0}(t) \rangle \\ &= -\lim_{\epsilon \rightarrow 0} \int_{-\infty}^{+\infty} \mathbf{x}''(t) \frac{\sin((t-t_0)\pi\epsilon^{-1})}{\pi(t-t_0)} d\mu(t) \\ &= -\lim_{\epsilon \rightarrow 0} \int_{-\infty}^{+\infty} \mathbf{x}(t) \left[ \frac{\sin((t-t_0)\pi\epsilon^{-1})}{\pi(t-t_0)} \right]'' d\mu(t) \\ &\approx -(\alpha_{-k}\mathbf{x}(t_0 - kh) + \dots + \alpha_0\mathbf{x}(t_0) + \dots + \alpha_k\mathbf{x}(t_0 + kh)), \end{aligned}$$

where

$$\alpha_j = \mu(I_j) \cdot \left[ \frac{\sin((t-t_0)\pi\epsilon^{-1})}{\pi(t-t_0)} \right]'' \Big|_{t=t_0+jh}.$$

$[\alpha_{-k} \cdots \alpha_{-1} \quad \alpha_0 \quad \alpha_1 \cdots \alpha_k]$  is our **stencil** for the Toeplitz.

## Signed measures - 1/2

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$$\alpha_j = \mu(I_j) \cdot \left[ \frac{\sin((t - t_0)\pi\epsilon^{-1})}{\pi(t - t_0)} \right]''_{|t=t_0+jh},$$

$$\begin{cases} \mu(I_j) > 0 & \text{always} \\ \left[ \frac{\sin((t - t_0)\pi\epsilon^{-1})}{\pi(t - t_0)} \right]''_{|t=t_0+jh} & \text{changes sign.} \end{cases}$$

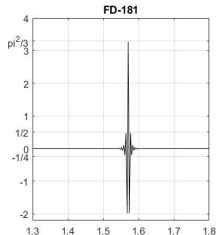
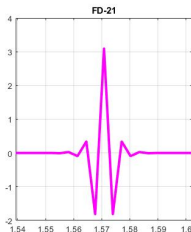
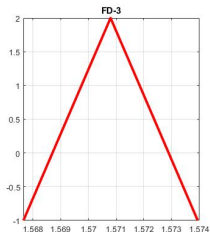
Is it so dramatic that the sequence  $\alpha_j$  change signes?

### Remark

The Lebesgue measure  $d\mu(\cdot)$  on  $[0, 1]$  can be weakly approximated by *signed* measures:  $d\mu(\cdot) = \lim_{n \rightarrow \infty} n^{-1} \frac{\sin(t\pi n)}{\pi t} d\mu(\cdot)$ .

## Signed measures - 2/2

**Fact:** the spectrum of the graph-Laplacian that arises from FD schemes with increasing connected points, converges to the spectrum of the continuous Laplacian operator.



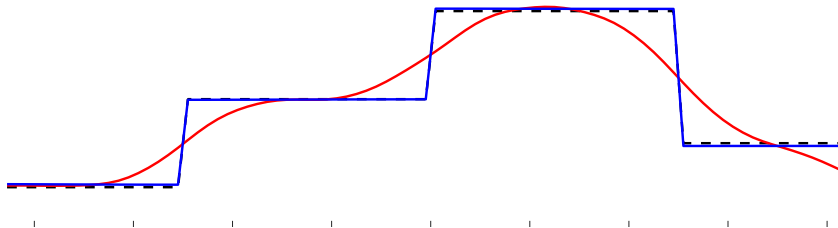
The stencil converges to the Fourier coefficients of  $f(\theta) = \theta^2$ :

$$\left[ \cdots \quad -\frac{1}{4} \quad \frac{1}{2} \quad -2 \quad \frac{\pi^2}{3} \quad -2 \quad \frac{1}{2} \quad -\frac{1}{4} \quad \cdots \right]$$

## Example - heat( $n, 1$ ) 5% noise

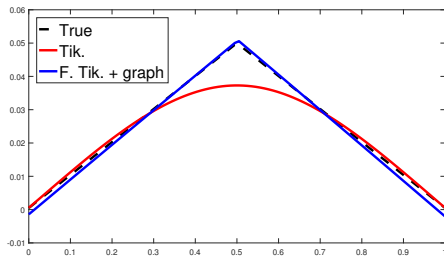
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graph-Laplacian with 10 points connected.  
No regularization parameters setting



$$L_w^{(n)} = \text{diag} \left( L_w^{(n/4)}, L_w^{(n/4)}, L_w^{(n/4)}, L_w^{(n/4)} \right)$$

## Example - deriv2(n, 3), 2% noise

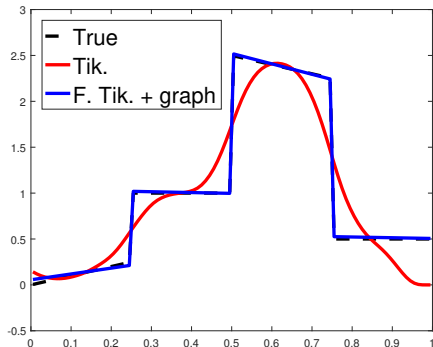


$$L_w^{(n)} = \begin{bmatrix} L_w^{(n/2)} & 0 \\ 0 & L_w^{(n/2)} \end{bmatrix} \quad L_w^{(n/2)} = \begin{bmatrix} 0 & 0 & \cdots & \cdots & 0 \\ -1 & 2 & -1 & \cdots & 0 \\ & \ddots & \ddots & \ddots & \\ & & -1 & 2 & -1 \\ 0 & 0 & \cdots & \cdots & 0 \end{bmatrix}$$

$$\ker(L_w^{(n/2)}) = \text{Span}\{\vec{1}, \vec{t}\}$$

## Example - heat( $n, 1$ ) 2% noise

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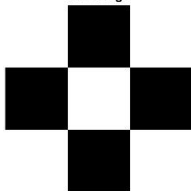




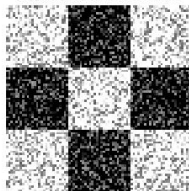
## 2D example - denosing 1/2

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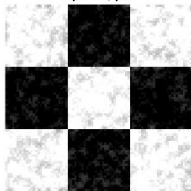
real image



50% of Gaussian white noise



alpha=1, p=1



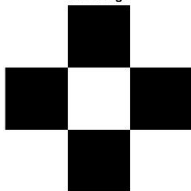
alpha=1, p=10



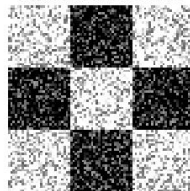
## 2D example - denoising 2/2

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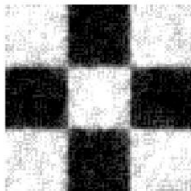
real image



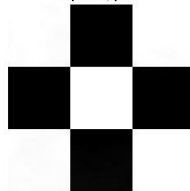
50% of Gaussian white noise



l2-TV



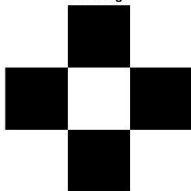
alpha=1, p=10



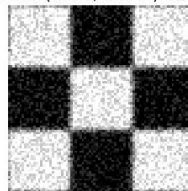
## 2D example - Gaussian blur

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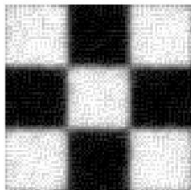
real image



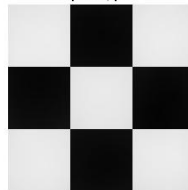
Gaussian blur (band=3, delta=1.1) 20% of g.w.n.



l2-TV

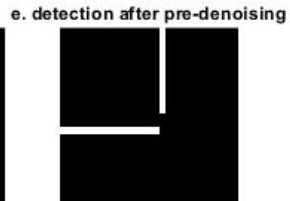
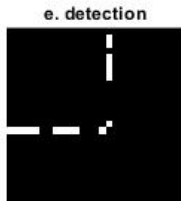
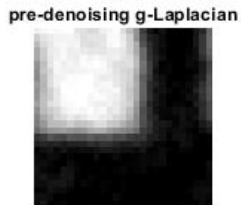
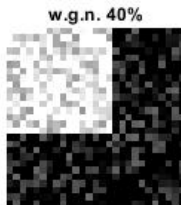
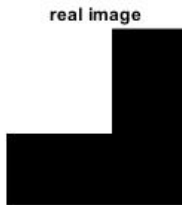


alpha=1, p=10



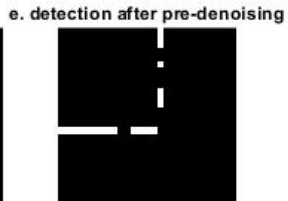
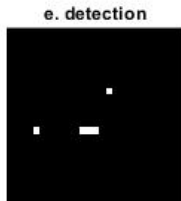
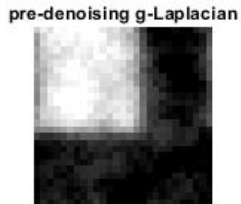
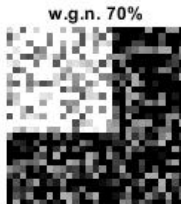
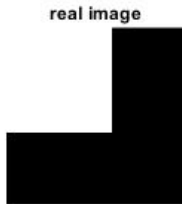
## Edge detection - 1/2

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## Edge detection - 2/2

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## Some references

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