

# Prediction mimicking Gaussian model

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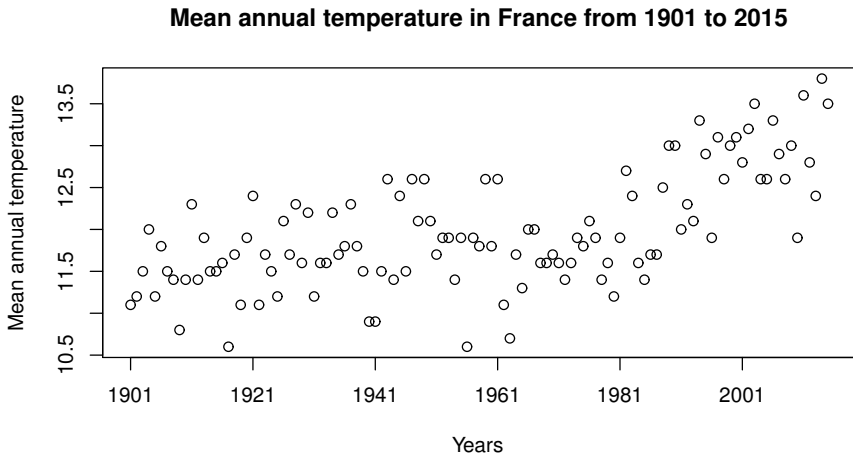
Having the time series

$$\mathbf{s}^{(n)} = (s_1, \dots, s_n)^\top \in \mathbb{R}^n \quad \text{column vector,}$$

how to predict the next observation  $s_{n+1}$  ?

# Example

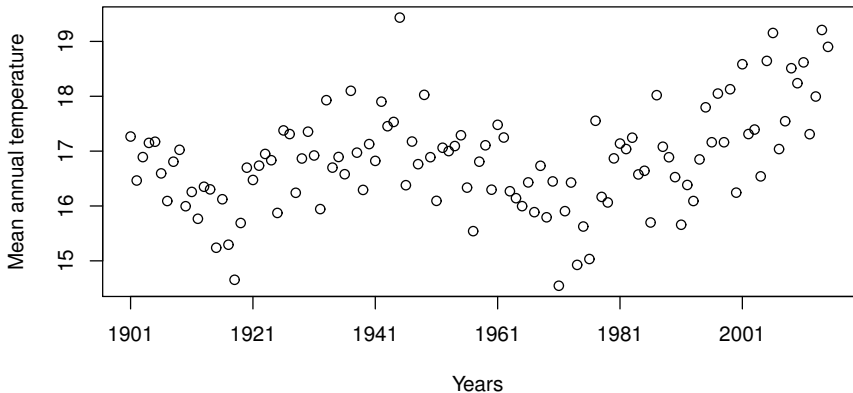
Figure : Mean annual temperatures in France from 1901 to 2015.



# Example

Figure : Mean annual temperatures in Morocco from 1901 to 2015.

## Mean annual temperature in Morocco from 1901 to 2015



$$\hat{s}_{n+1} = g(n+1 | s_1, \dots, s_n).$$

The maps  $g(\cdot | s_1, \dots, s_n) : [1, n+1] \rightarrow \mathbb{R}$  are given by a wide variety of methods, e.g.

Take a good function  $g(\cdot | s_1, \dots, s_n) : [1, n + 1] \rightarrow \mathbb{R}$  such that  $g(i | s_1, \dots, s_n) = s_i$ , with  $i = 1, \dots, n$ .

$$\begin{aligned}g(\cdot | s_1, \dots, s_n) &= \arg \min_{h \in \mathcal{F}} \left\{ \sum_{i=1}^n |h(i) - s_i|^2, \right. \\ &\quad \left. C(h) \leq \delta \right\} \\ &= \arg \min_{h \in \mathcal{F}} \left\{ \sum_{i=1}^n |h(i) - s_i|^2 + \lambda C(h) \right\}.\end{aligned}$$

$f(s_1, \dots, s_{n+1}, \theta) \geq 0$  is a PDF on  $\mathbb{R}^{n+1}$  if

$$\int_{\mathbb{R}^{n+1}} f(s_1, \dots, s_{n+1}, \theta) ds_1 \dots ds_{n+1} = 1.$$



Each PDF  $f(s_1, \dots, s_{n+1}, \theta)$  on  $\mathbb{R}^{n+1}$  produces two predictors :

$$s(n+1, CEXP) =: \frac{\int_{\mathbb{R}} s_{n+1} f(s_1, \dots, s_{n+1}, \theta) ds_{n+1}}{\int_{\mathbb{R}} f(s_1, \dots, s_{n+1}, \theta) ds_{n+1}}$$

= conditional expectation.

$$s(n+1, MAP) =: \arg \max \{ f(s_1, \dots, s_{n+1}, \theta) : s_{n+1} \in \mathbb{R} \}$$

= maximum a posteriori.

# Theoretical performance

Using the PDF  $f$ , we generate a sequence  $(s_1^1, \dots, s_{n+1}^1), \dots, (s_1^N, \dots, s_{n+1}^N)$  with  $N$  very large such that

$$\begin{aligned} & \frac{1}{N} \sum_{i=1}^N |s_{n+1}^i - s^i(n+1, CEXP)|^2 \\ & \approx \min \left\{ \frac{1}{N} \sum_{i=1}^N |s_{n+1}^i - g(s_1^i, \dots, s_n^i)|^2 : g \right\} \\ & \approx \int_{\mathbb{R}^{n+1}} (s_{n+1} - s(n+1, CEXP))^2 f(s_1, \dots, s_{n+1}, \theta) ds_1 \dots ds_{n+1}, \end{aligned}$$

Theoretical mean squared prediction error (TMSPE).

If

$$f(s_1, \dots, s_{n+1}, \mathbf{P}^{(n+1)}) = \sqrt{\frac{\det(\mathbf{P}^{(n+1)})}{(2\pi)^{n+1}}} \exp\left\{-\frac{(\mathbf{s}^{(n+1)})^\top \mathbf{P}^{(n+1)} \mathbf{s}^{(n+1)}}{2}\right\},$$

with  $\mathbf{P}^{(n+1)} = [p_{ij} : i, j = 1, \dots, n+1]$  symmetric and positive definite matrix (precision matrix).

$$\mathbf{C}^{(n+1)} = [c_{ij} : i, j = 1, \dots, n+1] = \{\mathbf{P}^{(n+1)}\}^{-1}$$

:= covariance matrix.

$$\mathbf{C}^{(n)} = [c_{ij} : i, j = 1, \dots, n].$$

$$c_{i*} =: (c_{i1}, \dots, c_{in}), \quad i = 1, \dots, n+1.$$

We have

$$\begin{aligned} s(n+1, CEXP) &= s(n+1, MAP) = \mathbf{c}_{n+1*} \{ \mathbf{C}^{(n)} \}^{-1} \mathbf{s}^{(n)} \\ &= \arg \min \{ (\mathbf{s}^{(n+1)})^\top \mathbf{P}^{(n+1)} \mathbf{s}^{(n+1)} : \mathbf{s}_{n+1} \in \mathbb{R} \}. \end{aligned}$$

$$\begin{aligned} \frac{1}{N} \sum_{i=1}^N |s_{n+1}^i - s^i(n+1, CEXP)|^2 &\approx c_{n+1n+1} - c_{n+1*} \{C^{(n)}\}^{-1} c_{n+1*}^T \\ &= \frac{\det(C^{(n+1)})}{\det(C^{(n)})}. \end{aligned}$$

# Popular Gaussian model and cubic splines

$$\int_1^{n+1} |s''(t)|^2 dt = (\mathbf{s}^{(n+1)})^\top \mathbf{Q}^{(n+1)} \mathbf{s}^{(n+1)},$$
$$\mathbf{C}^{(n+1)} = \sigma_s^2 (\mathbf{Q}^{(n+1)})^{ginv} + \sigma_w^2 \mathbf{I}_{n+1},$$

Parameters :  $\sigma_s^2$ ,  $\sigma_w^2$  and  $(\mathbf{Q}^{(n+1)})^{ginv}$ .

Dermoune, Preda, JMVA 2016.

Dermoune, Rahmania, Wei, JMVA 2013.

# Popular Gaussian model and Gaussian kernel

$$k(i, j) = \exp\left(-\frac{|i - j|^2}{\sigma^2}\right),$$

$$\mathbf{K}^{(n+1)} = [k(i, j) : i, j = 1, \dots, n + 1],$$

$$\mathbf{C}^{(n+1)} = \sigma_s^2 \mathbf{K}^{(n+1)} + \sigma_w^2 \mathbf{I}_{n+1},$$

three parameters  $\sigma^2$ ,  $\sigma_s^2$  and  $\sigma_w^2$ .

# Gaussian model and interpolation

Let  $\mathbf{c}_j$  be the  $j$ -th column of the covariance matrix  $\mathbf{C}^{(n+1)}$ , and let us consider the set of functions  $\text{span}(\mathbf{c}_1, \dots, \mathbf{c}_n)$  :

$$\mathbf{g}_\beta = \sum_{j=1}^n \beta_j \mathbf{c}_j : i \in [1, n+1] \rightarrow \sum_{j=1}^n \beta_j c_{ij} = g_\beta(i).$$

The unique element of  $\text{span}(\mathbf{c}_1, \dots, \mathbf{c}_n)$  such that

$$g_\beta(i) = s_i, \quad i = 1, \dots, n,$$

is given by

$$(\beta_1^*, \dots, \beta_n^*)^\top = \{\mathbf{C}^{(n)}\}^{-1} \mathbf{s}^{(n)},$$

and then

$$g_{\beta^*}(n+1) = s(n+1, \text{CEXP}) \quad \text{Gaussian predictor.}$$



# Model mimicking Gaussian model :Dermoune, Es-sbaye, Es-sbaye, Moustaid, ArXiv 2018

Let  $\mathbf{B}^{(n+1)} = (\mathbf{b}_1, \dots, \mathbf{b}_{n+1})$  be a basis of  $\mathbb{R}^{n+1}$  such that the sub-matrix  $\mathbf{B}^{(n)} =: [b_{ij} : i, j = 1, \dots, n]$  is invertible with  $\Theta$  its inverse and  $\theta_j$  denotes its  $j$ -th row. Let us consider the set of functions  $\text{span}(\mathbf{b}_1, \dots, \mathbf{b}_n)$  :

$$\mathbf{g}_\beta = \sum_{j=1}^n \beta_j \mathbf{b}_j : i \in [1, n+1] \rightarrow \sum_{j=1}^n \beta_j b_{ij} = g_\beta(i).$$

# Model mimicking Gaussian model

The unique element of  $\text{span}(\mathbf{b}_1, \dots, \mathbf{b}_n)$  such that

$$\mathbf{g}_\beta(i) = s_i, \quad i = 1, \dots, n,$$

is given by

$$(\beta_1^*, \dots, \beta_n^*)^\top = \Theta \mathbf{s}^{(n)},$$

and then

$$\mathbf{g}_{\beta^*}(n+1) = \sum_{j=1}^n \theta_j \mathbf{s}^{(n)} b_{n+1j} = s(n+1, \text{CEXP})$$

when  $\mathbf{B}^{(n+1)}$  is a covariance matrix.

# Important observation

We showed for the annual mean temperature that

$$g_{\beta^*}(n+1) = \sum_{j=1}^n \theta_j^{(n)} s^{(n)} b_{n+1j}^{(n+1)}$$

is a bad predictor when  $\mathbf{B}^{(n+1)}$  is not a covariance matrix. However with the normalization

$$\frac{\sum_{j=1}^n \theta_j^{(n)} s^{(n)} b_{n+1j}^{(n+1)}}{\sum_{j=1}^n \theta_j^{(n)} \mathbf{1}^{(n)} b_{n+1j}^{(n+1)}} =: \sum_{i=1}^n w_i^{(n)} s_i$$
$$= \mathbf{w}^{(n)} \mathbf{s}^{(n)}$$

the new predictor becomes good.

# Model mimicking Gaussian model : Backward model

Given a  $n + 1 \times n + 1$  matrix  $\mathbf{B}^{(n+1)} = [b_{ij} : i, j = 1, \dots, n + 1]$  such that the sub-matrices  $\mathbf{B}^{(k)} = [b_{ij} : i, j = 1, \dots, k]$  are invertible, with  $k = 2, \dots, n$ . The inverse  $\{\mathbf{B}^{(k)}\}^{-1} =: \Theta^{(k)}$ . We predict  $s_{k+1}$  by

$$\begin{aligned}\hat{s}_{k+1} &= \frac{\sum_{j=1}^k b_{k+1j} \theta_j^{(k)} s^{(k)}}{\sum_{j=1}^k b_{k+1j} \theta_j^{(k)} \mathbf{1}^{(k)}} \\ &=: \mathbf{w}^{(k)} \mathbf{s}^{(k)},\end{aligned}$$

with  $k = 2, \dots, n$ .

# Model mimicking Gaussian model : Forward model

For each  $k = 2, \dots, n$ , we give a  $k + 1 \times k + 1$  matrix  $\mathbf{B}^{(k+1)} = [b_{ij}^{(k+1)} : i, j = 1, \dots, k + 1]$  such that the sub-matrix  $\mathbf{B}^{(k)} = [b_{ij}^{(k+1)} : i, j = 1, \dots, k]$  is invertible. Its inverse  $\{\mathbf{B}^{(k)}\}^{-1} =: \Theta^{(k)}$ . We predict  $s_{k+1}$  by

$$\begin{aligned}\hat{s}_{k+1} &= \frac{\sum_{j=1}^k b_{k+1j}^{(k+1)} \theta_j^{(k)} \mathbf{s}^{(k)}}{\sum_{j=1}^k b_{k+1j}^{(k+1)} \theta_j^{(k)} \mathbf{1}^{(k)}} \\ &=: \mathbf{w}^{(k)} \mathbf{s}^{(k)},\end{aligned}$$

with  $k = 2, \dots, n$ .

# Linear model for prediction

A model  $\mathcal{M}$  for prediction is any sequence of weights  $(\mathbf{w}^{(k)} : k = 2, \dots, n)$ , with

$$\mathbf{w}^{(k)} \in \mathbb{R}^k, \quad \hat{s}_{k+1} = \mathbf{w}^{(k)} \mathbf{s}^{(k)} =: \sum_{i=1}^k w_i^{(k)} s_i.$$

$$MSPE =: \frac{\sum_{j=1}^{n-1} |s_{j+1} - \mathbf{w}^{(j)} \mathbf{s}^{(j)}|^2}{n-1},$$

$$MAXPE =: \max\{|s_{j+1} - \mathbf{w}^{(j)} \mathbf{s}^{(j)}| : j = 1, \dots, n-1\}.$$

# Comparison of two models

Let  $\{\mathcal{M}(m) : m = 1, 2\}$  be two models.

1) We say that  $\mathcal{M}(1)$  is better than  $\mathcal{M}(2)$  w.r.t. the MSPE criterion if

$$MSPE(\mathcal{M}(1)) < MSPE(\mathcal{M}(2)).$$

2) We say that  $\mathcal{M}(1)$  is better than  $\mathcal{M}(2)$  w.r.t. the MAXPE criterion if

$$MAXPE(\mathcal{M}(1)) < MAXPE(\mathcal{M}(2)).$$

3) We say that  $\mathcal{M}(1)$  is statistically better than  $\mathcal{M}(2)$  if

$$\frac{\sum_{k=1}^{n-1} \mathbf{1}_{[|s_{k+1} - \mathbf{w}^{(k)}(1)\mathbf{s}^{(k)}| < |s_{k+1} - \mathbf{w}^{(k)}(2)\mathbf{s}^{(k)}|]}}{n-1} > 1/2.$$



# Models using cubic splines

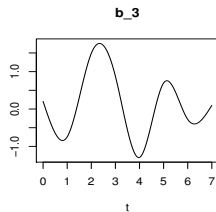
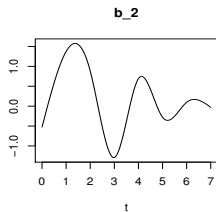
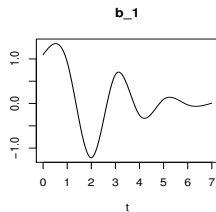
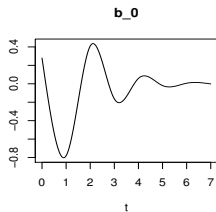
$\mathbb{R}^k = \mathcal{S}_3(1, \dots, k)$  the set of natural cubic splines,

$$\int_1^k |s(t)|^2 dt = \{\mathbf{s}^{(k)}\}^\top \mathbf{M}^{(k)} \mathbf{s}^{(k)} \quad \text{non symmetric matrix}$$
$$= \{\mathbf{s}^{(k)}\}^\top \mathbf{S}^{(k)} \mathbf{s}^{(k)} \quad \text{symmetric matrix.}$$

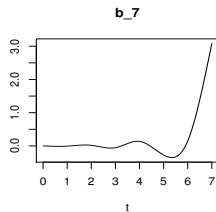
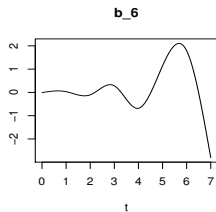
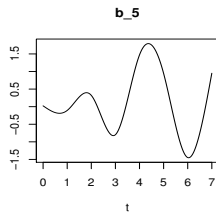
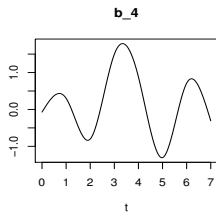
$$\mathbf{B}^{(k)} = \mathbf{M}^{(k)}, \{\mathbf{M}^{(k)}\}^{-1}, \mathbf{S}^{(k)}, \{\mathbf{S}^{(k)}\}^{-1},$$

with  $k = 1, \dots, n + 1$ .

$$B^{(k)} = M^{(k)}, k = 7.$$



# Numerical results : $B^{(k)} = M^{(k)}$ , $k = 7$



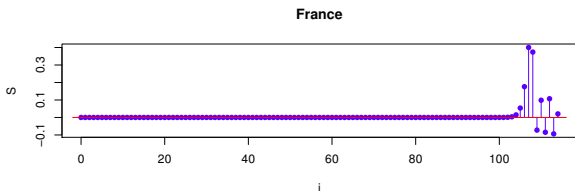
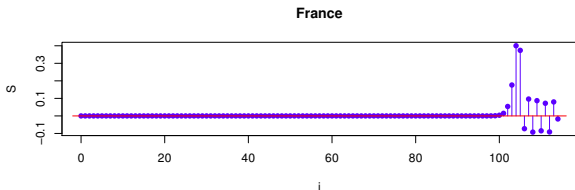
From each sequence of bases we constructed

$$8 + 4n + n(n + 2) \approx 10^4 \quad \text{models,}$$

with  $n = 115$ .

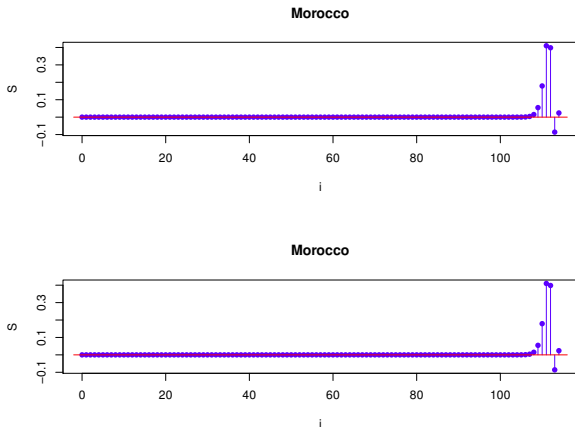
# Our optimal model among $8 + 4n + n(n + 2) \approx 10^4$ models

**Figure :** The optimal conservative row w.r.t. MAXPE, and statistical criterion in the case of France with  $n = 115$ .

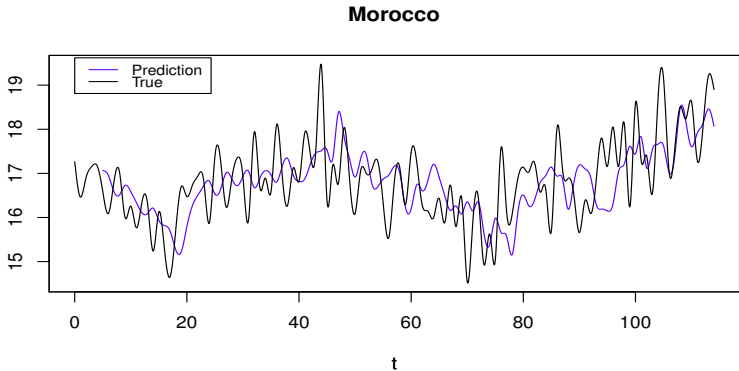


# Our optimal model among $8 + 4n + n(n + 2) \approx 10^4$ models

**Figure :** The optimal conservative row w.r.t. MAXPE, and statistical criterion in the case of Morocco with  $n = 115$ .

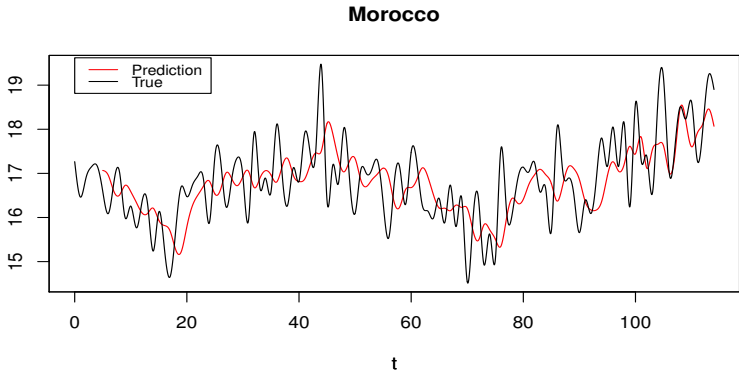


# Splines of the true temperature and its optimal predictors : Morocco





# Splines of the true temperature and its optimal predictors : Morocco



# Comparison with AR(1) model

**Table :** Comparison of AR(1) model and our optimal coherent sequences w.r.t. MAXPE.

<b>MAXPE criterion</b>		
Country	France	Morocco
Our optimal model	1.220770	1.917094
AR(1) model	1.433288	2.490254

# Comparison with AR(1) model

<b>Statistical criterion</b>		
Country	France	Morocco
The best	AR(1) model	Our optimal model

- We proposed a new method and models for prediction using only bases of the Euclidean spaces.
- We proposed comparison criteria for selecting the best model.
- We illustrated our method for the prediction of annual mean temperature of France and Morocco.

Thank you and many thanks for this perfect organization in this wonderful site.